

\*\*\*SPARE PART\*\*\* SIMOTION DRIVE-BASED CONTROL UNIT D425; PROGRAMMABLE MOTION CONTROLLER; BASIC PERFORMANCE; INTERFACES: 8 DI, 8 DI/DO, 4 DRIVE-CLIQ, 2 PROFIBUS, 2 ETHERNET, 2 USB, 1 OPTION SLOT



Figure similar

Article number	
product brandname	SIMOTION
Product type designation	D425
Performance class for motion control system	BASIC Performance
Version of the motion control system	Multiple-axis system

PLC and motion control performance	
Number of axes / maximum	16
Minimum PROFIBUS cycle clock	2 ms
Minimum PROFINET send cycle clock	0.5 ms
Minimum interpolator cycle clock	2 ms
Minimum servo cycle clock	2 ms

Integrated drive control	
Maximum number of axes for integrated drive control	
<ul style="list-style-type: none"> <li>• servo</li> <li>• vector</li> <li>• V/f</li> </ul>	<p>6</p> <p>4</p> <p>8</p>

- note

Alternative control modes; drive control based on SINAMICS S120 CU320, firmware version V2.x

## Memory

RAM (work memory)	48 Mbyte
Additional RAM work memory for Java applications	20 Mbyte
RAM disk (load memory)	29 Mbyte
Retentive memory	364 kbyte
Persistent memory (user data on CF)	300 Mbyte

## Communication

Interfaces	
• DRIVE-CLiQ	4
• USB	2
• Industrial Ethernet	2
• PROFIBUS	2
— note	Equidistant and isochronous; Can be configured as master or slave
• PROFINET	0
— note	Optional via CBE30; 1 interface with 4 ports; supports PROFINET IO with IRT and RT; configurable as a PROFINET IO controller and/or device

## General technical data

Fan	Optional fan/battery module (single fan)
DC supply voltage	
• rated value	24 V
• minimum	20.4 V
• maximum	28.8 V
Consumed current / typical	600 mA
• Note	with no load on inputs/outputs, no 24 V supply via DRIVE-CLiQ and PROFIBUS interface
Making current, typ.	6 A
Power loss [W] / typical	15 W
Ambient temperature, during	
• storage	-40 ... +70 °C
• transport	-40 ... +70 °C
• operation	0 ... 55 °C
— note	Maximum 5000 m (16405 ft) above sea level. Above an altitude of 2000 m (6562 ft), the max. ambient temperature decreases by 7 °C (12.6 °F) every 1000 m (3281 ft).
Relative humidity	
• during operation	5 ... 95 %
• without condensation, tested acc. to IEC 60068-2-38	Wert fehlt
Air pressure	700 ... 1 060 hPa

Degree of protection	IP20
Height	380 mm
Width	50 mm
Depth	270 mm
<ul style="list-style-type: none"> <li>Note</li> </ul>	When the spacer is removed 230 mm (9.05 in) deep
Net weight	2 700 g

Digital inputs	
Number of digital inputs	8
DC input voltage	
<ul style="list-style-type: none"> <li>rated value</li> </ul>	24 V
<ul style="list-style-type: none"> <li>for signal "1"</li> </ul>	15 ... 30 V
<ul style="list-style-type: none"> <li>for signal "0"</li> </ul>	-3 ... +5 V
Electrical isolation	Yes
<ul style="list-style-type: none"> <li>note</li> </ul>	Yes, in groups of 4
Current consumption for "1" signal level, typ.	10 mA
Input delay time for	
<ul style="list-style-type: none"> <li>signal "0" → "1", typ.</li> </ul>	50 μs
<ul style="list-style-type: none"> <li>signal "1" → "0", typ.</li> </ul>	150 μs

Digital inputs/outputs	
Number of digital I/Os	8
Parameterization possibility of the digital I/Os	parameterizable as DI, as DO, as measuring input input (max. 6), as output of output cam (max. 8)

If used as an input	
DC input voltage	
<ul style="list-style-type: none"> <li>rated value</li> </ul>	24 V
<ul style="list-style-type: none"> <li>for signal "1"</li> </ul>	15 ... 30 V
<ul style="list-style-type: none"> <li>for signal "0"</li> </ul>	-3 ... +5 V
Electrical isolation	No
Current consumption for "1" signal level, typ.	10 mA
Input delay time for	
<ul style="list-style-type: none"> <li>signal "0" → "1", typ.</li> </ul>	5 μs
<ul style="list-style-type: none"> <li>signal "1" → "0", typ.</li> </ul>	50 μs
Measuring input / reproducibility	5 μs

If used as an output	
Load voltage	
<ul style="list-style-type: none"> <li>rated value</li> </ul>	24 V
<ul style="list-style-type: none"> <li>minimum</li> </ul>	20.4 V
<ul style="list-style-type: none"> <li>maximum</li> </ul>	28.8 V
Electrical isolation	No
Current carrying capacity for each output, max.	500 mA
Leakage current, max.	2 mA

Output delay for	
<ul style="list-style-type: none"> <li>• signal "0" → "1", typ.</li> <li>• signal "0" → "1", max.</li> <li>• signal "1" → "0", typ.</li> <li>• signal "1" → "0", max.</li> <li>— note</li> </ul>	<p>150 μs</p> <p>400 μs</p> <p>75 μs</p> <p>100 μs</p> <p>Data for Vcc = 24 V; load 48 Ohm; "1" = 90 % VOut, "0" = 10 % VOut</p>
Cam output	
<ul style="list-style-type: none"> <li>• reproducibility</li> </ul>	125 μs
Switching frequency of the outputs for	
<ul style="list-style-type: none"> <li>• resistive load, max.</li> <li>• inductive load, max.</li> <li>• lamp load, max.</li> </ul>	<p>100 Hz</p> <p>2 Hz</p> <p>11 Hz</p>
Short-circuit protection	Yes

### Additional technical data

Back-up of non-volatile data	
<ul style="list-style-type: none"> <li>• of retentive data</li> <li>• of real-time clock, min.</li> <li>• note</li> </ul>	<p>at least 5 days</p> <p>5 d</p> <p>longer buffer duration of the retentive data and the real-time clock using a battery inserted in the fan/battery module</p>
Approvals	
<ul style="list-style-type: none"> <li>• USA</li> <li>• Canada</li> <li>• Australia</li> </ul>	<p>cULus</p> <p>cULus</p> <p>RCM (formerly C-Tick)</p>